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## Tests of the "Beta Model"

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The general stochastic learning models that have been previously studied [1] postulate a probability distribution

$$
\boldsymbol{p}_{n}=\left\{p_{n}(1), p_{n}(2), \cdots, p_{n}(r)\right\}
$$

over the set of $r$ alternatives available to an organism. This vector gives the probability that each alternative will be chosen on trial $n$. A transition operator $\boldsymbol{T}$ is postulated such that (i) $\boldsymbol{T}$ does not depend upon $\boldsymbol{n}$ (independence of path); (ii) $\boldsymbol{T}$ depends upon the choice made on trial $n$ and on the outcome; and (iii) $\boldsymbol{p}_{n+1}=\boldsymbol{T} \boldsymbol{p}_{n}$.

For the most part linear (matrix) operators have been studied-partly because their mathematical properties are comparatively simple, partly because of Estes' stimulus-sampling rationale [3], and partly because the combining-ofclasses condition ([1], [2]) leads to a particular type of linear operator. Nonetheless, it is still an open question whether linearity is a tenable assumption or whether one of the possible nonlinear operators will be better able to describe data. The problem, of course, is how to select among all the possible nonlinear operators.
The purpose of this paper is to study some properties of a nonlinear model, called the beta model, and to apply it to three published experiments (Chapter 14 and [6]). The linear model, called the alpha model, and the beta model can both be arrived at from the same general considerations. For this reason, comparisons between these two models are made.

## Response-Strength Models

Some learning theorists ([4], [7]) consider response frequencies and their underlying probabilities to be the manifestation in behavior of some latent construct called response strength. Earlier stochastic learning models have
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been criticized for their failure to postulate the source of the response probabilities with which they deal. Recently, the response-strength notion has been formalized [5]; we review it briefly here and then investigate some of its consequences.

Suppose that $i$ is an alternative in the set $S$, which, in turn, is a subset of the finite set $T$. Let $P_{S}(i)$ denote the probability that $i$ is chosen when the choice is confined to $S$ and $P_{T}(i \mid S)$, the probability that $i$ is chosen when the choice is confined to $T$, conditional on its being in $S$. If $P_{[t, j)}(i) \neq 0$ or 1 , where $i$ and $j$ are in $T$, then we postulate

$$
P_{S}(i)=P_{T}(i \mid S) .
$$

This axiom leads to the conclusion that there exists a ratio scale, $v$, over the alternatives with the properties

$$
\begin{equation*}
P_{S}(i)=\frac{v(i)}{\sum_{y \in S} v(y)}, \tag{1}
\end{equation*}
$$

and

$$
\begin{equation*}
v(i)>0, \quad \text { for all } i \in T . \tag{2}
\end{equation*}
$$

This $v$-scale, which in psychophysical problems appears to be closely related to scales that have been studied earlier, is presumed to be the formal counterpart of response strength. For many purposes, this scale may be more useful than the choice probabilities themselves.
In most learning experiments the set of alternatives is fixed, and so one cannot make a direct check of the axiom that leads to the $v$-scale; however, since this axiom refers to an organism, not to an experiment, it is meaningful to study its consequences for learning. We formulate the learning process as sequential transitions of the $v$-vector, and let this stochastic process indirectly determine the response probabilities via Equation 1.

Let $\boldsymbol{v}_{n}=\left\{v_{n}(1), v_{n}(2), \cdots, v_{n}(r)\right\}$ denote this vector on trial $n$ and let $\boldsymbol{T}$ now denote a path-independent operator at the level of the $v$ 's. The transition equation is

$$
\begin{equation*}
\boldsymbol{v}_{n+1}=\boldsymbol{T} \boldsymbol{v}_{n} \tag{3}
\end{equation*}
$$

The problem is to restrict $\boldsymbol{T}$. By Equation 2, the $v$ 's must be positive; hence, if $\boldsymbol{T v}$ is a distribution of $v$-values, we must have

$$
\begin{equation*}
\boldsymbol{T} v>0, \text { if } v>0, \tag{4}
\end{equation*}
$$

where 0 is the $r$-dimensional zero vector. A second condition stems from the fact that $v$ is a ratio scale; therefore, we can multiply all values in the model by any positive constant $k$. In particular, the equality in Equation 3 should not be affected, so we must have

$$
\begin{equation*}
k \boldsymbol{T} \boldsymbol{v}_{n}=\boldsymbol{T} k \boldsymbol{v}_{n}, \quad \text { if } k>0 \tag{5}
\end{equation*}
$$

This has been called the independence-of-unit condition. If it is not met, then in principle we could determine the unit of the $v$-scale from learning
data. These first two limitations seem basic to the way our problem is formulated. However, Equations 4 and 5 do not narrow down $T$ sufficiently, and, unfortunately, no other conditions seem to follow from the basic choice axiom. Thus, we are forced to make substantive assumptions that are suggested largely by mathematical considerations. First, we note that Equation 5 is one of the two properties that are usually used in defining a linear transformation; the other is

$$
\begin{equation*}
\boldsymbol{T}\left(\boldsymbol{v}+\boldsymbol{v}^{*}\right)=\boldsymbol{T} \boldsymbol{v}+\boldsymbol{T} \boldsymbol{v}^{*}, \quad \text { if } \boldsymbol{v}, \boldsymbol{v}^{*}>0 \tag{6}
\end{equation*}
$$

Often this is called the superposition condition. Even though it is difficult to give an intuitive interpretation for Equation 6 because the addition of two $v$-vectors does not correspond naturally to any experimental manipulation, we shall impose the condition.

Finally, we shall assume that any positive real number is a possible $v$-scale value; hence, there is no upper bound to the possible values. This assumption together with Equations 5 and 6 implies that the transformation $\boldsymbol{T}$ must be a matrix operator $T$, in which case Equation 3 becomes the matrix equation

$$
(7) \quad v_{n+1}=T v_{n}
$$

where $\boldsymbol{v}$ denotes a column vector. Equation 4 implies that $T$ is nonsingular and has nonnegative entries.

The Two-Alternative Alpha Model. For two alternatives, Equation 7 becomes

$$
\left[\begin{array}{l}
v_{n+1}(1)  \tag{8}\\
v_{n+1}(2)
\end{array}\right]=\left[\begin{array}{ll}
t_{11} & t_{12} \\
t_{21} & t_{22}
\end{array}\right]\left[\begin{array}{l}
v_{n}(1) \\
v_{n}(2)
\end{array}\right] .
$$

Although, in principle, we could work with Equation 8 in its full generality, in practice there are too many parameters. Each operator has four, and there is usually more than one operator. So we are forced to consider further restrictions.

A question that immediately comes to mind is whether there is any specialization that leads to an operator that is linear in the probabilities. It is not difficult to show (see [5]) that a necessary and sufficient condition is that the column sums of $T$ be equal, i.e.,

$$
\begin{equation*}
t_{11}+t_{21}=t_{12}+t_{22} \tag{9}
\end{equation*}
$$

This specialization is the alpha model. Observe that Equation 9 implies that the sum of the scale values on trial $n+1$ is simply $t_{11}+t_{21}$ times the sum of the scale values on trial $n$. This means that, independent of how the total scale value is distributed between the two alternatives, experience on a given trial augments or diminishes that sum by a fixed factor; however, the change in the scale value for a particular alternative is not independent of the distribution over the alternatives. Thus, for example, if alternative 1 is chosen and rewarded on trial $n, v_{n+1}(1)$ depends not only upon $v_{n}(1)$ but also upon $v_{n}(2)$ (the propensity to choose alternative 2).

The Two-Alternative Beta Model. The last observation suggests the other
model that we examine. We postulate that $v_{n+1}(i)$ depends upon $v_{n}(i)$, but not upon the scale value of the other alternative. This means that the matrix $T$ in Equation 8 must be diagonal, i.e.,

$$
\begin{equation*}
v_{n+1}(1)=t_{11} v_{n}(1), \quad v_{n+1}(2)=t_{22} v_{n}(2) \tag{10}
\end{equation*}
$$

From Equation 1 and Equation 10 we have

$$
\begin{aligned}
p_{n+1}(1) & =\frac{v_{n+1}(1)}{v_{n+1}(1)+v_{n+1}(2)}=\frac{t_{11} v_{n}(1)}{t_{11} v_{n}(1)+t_{2 \pm} v_{n}(2)} \\
& =\frac{\beta \frac{v_{n}(1)}{v_{n}(2)}}{\beta \frac{v_{n}(1)}{v_{n}(2)}+1}
\end{aligned}
$$

where $\beta=t_{11} / t_{22}$. But

$$
\frac{v_{n}(1)}{v_{n}(2)}=\frac{p_{n}(1)}{1-p_{n}(1)}
$$

so

$$
\begin{equation*}
p_{n+1}(1)=\frac{\beta p_{n}(1)}{(\beta-1) p_{n}(1)+1} \tag{11}
\end{equation*}
$$

Of course,

$$
p_{n+1}(2)=1-p_{n+1}(1)=\frac{p_{n}(2)}{p_{n}(2)+\beta\left[1-p_{n}(2)\right]}
$$

We observe that, like the alpha model, the beta model can be expressed in terms of path-independent operators acting upon the probabilities. So both models are path-independent at both the level of the $v$ 's and the level of the $p$ 's, both are linear at the level of the $v$ 's, but only the alpha model is also linear at the level of the $p$ 's. ${ }^{2}$

For experiments in which one outcome always follows alternative 1 and another outcome always follows alternative 2, the transition law for $p_{n}=p_{n}(2)$ is

$$
p_{n+1}= \begin{cases}\frac{p_{n}}{p_{n}+\beta_{1}\left(1-p_{n}\right)} & \text { if alternative } 1 \text { occurs }  \tag{12}\\ \frac{p_{n}}{p_{n}+\beta_{2}\left(1-p_{n}\right)} & \text { if alternative } 2 \text { occurs }\end{cases}
$$

Because $p_{n}$ is the probability of an error, we anticipate that $\beta_{1}>1$ and $\beta_{2}>1$.
${ }^{2}$ In [5], a somewhat different derivation of the beta model is given, based, in essence, on the condition leading to Equation 10. This condition, without explicitly assuming superposition, then leads to Equation 10. One merit of this approach is that it suggests a third model which differs from the beta model only in that the unboundedness condition is replaced by the condition that the $v$ 's are bounded from above. This model is linear and path-independent at the level of the $v$ 's, but is not path-independent at the level of the $p$ 's.

## Estimation of Beta-Model Parameters

To estimate model parameters from a set of data, it is useful-and with three or more parameters, almost essential-to have explicit formulas for properties of the model as functions of its parameters. These functions may then be equated to the corresponding statistics of the data and solved to give estimates of the parameters. Preferably, these expressions should be in closed form, but infinite series are acceptable since tables can be prepared. For the alpha model restricted in various ways, a number of closed expressions are known and several tables have been published. For the beta model, the situation is far less satisfactory because its nonlinearity makes it very difficult to calculate expected values. In fact, for two alternatives with partial reinforcement of each, no computable expression is known for any property of the model. If, however, we are willing to confine our attention to those experiments in which one of the alternatives, say 2 , is never rewarded, then a series can be developed for the expected number of trials before the other alternative is chosen. This can be used not only with experiments in which alternative 1 is always rewarded and 2 never rewarded ( $100: 0$ experiments), but also with experiments in which alternative 1 is rewarded with probability $\pi$ while alternative 2 is never rewarded ( $50: 0$ experiments, for example).

Let $p_{n}$ denote the probability that alternative 2 is chosen (i.e., an error is made) on trial $n$, and let $\nu+1$ denote the trial number when alternative 1 is first chosen (i.e., the trial number of the first success). Thus, $\nu$ denotes the number of trials before the first success. Because these trials are independent,

$$
\operatorname{Pr}(\nu=k)=\prod_{i=1}^{k} p_{i}\left(1-p_{k+1}\right) .
$$

Hence,

$$
\begin{equation*}
E(\nu)=\sum_{k=1}^{\infty} k \operatorname{Pr}(\nu=k)=\sum_{k=1}^{\infty} k\left(1-p_{k+1}\right) \prod_{i=1}^{k} p_{i} . \tag{13}
\end{equation*}
$$

Let $\beta$ denote the beta-model parameter of the (nonreward) operator that is always applied when alternative 2 is chosen. By induction on Equation 12 it is clear that for any $n \leqq \nu+1$,

$$
\begin{equation*}
p_{n+1}=\frac{v}{v+\beta^{n}}, \tag{14}
\end{equation*}
$$

where we have defined $v=v_{1}(2) / v_{1}(1)=p_{1} /\left(1-p_{1}\right)$. Substituting Equation 14 in Equation 13, we obtain

$$
\begin{align*}
E(\nu) & =\sum_{k=1}^{\infty} k\left[1-\frac{v}{v+\beta^{k}}\right] \prod_{i=1}^{k}\left[\frac{v}{v+\beta^{i}}\right]  \tag{15}\\
& =\sum_{k=1}^{\infty} k\left[\frac{\beta^{k}}{v+\beta^{k}}\right] \frac{v^{k}}{\prod_{i=1}^{k}\left(v+\beta_{0}^{l-1}\right)}
\end{align*}
$$

$$
=\sum_{k=1}^{\infty} \frac{k \beta^{k} v^{k}}{\prod_{j=0}^{k}\left(v+\beta^{\jmath}\right)}=\sum_{k=1}^{\infty} \frac{k \beta^{k}\left[\frac{p_{1}}{1-p_{1}}\right]^{k}}{\prod_{j=0}^{k}\left[\frac{p_{1}}{1-p_{1}}+\beta^{\jmath}\right]} .
$$

The final infinite series for the expected number of trials before the first success, which is an example of a function we denote by $L(p, \beta)$, can be computed to any degree of accuracy for any $p$ and $\beta$. This is not simple, however, when both parameters are near 1; for example, when $p=0.9995$ and $\beta=1.03$, one needs 227 terms to obtain accuracy in the third decimal place. For the experiments that we will analyze, $p$ is very close to 1 ; hence, we were led to have a table of $L(p, \beta)$ prepared by the Univac computer at the University of Pennsylvania. The table is given at the end of this paper.

With a value of $E(\nu)$, Equation 15 imposes a relationship between $p$ and $\beta$, but it does not specify either parameter uniquely. Thus, one must either estimate one of the parameters independently or undertake a trial-and-error exploration of the parameter space using Monte Carlo methods (to match other statistics of the data, such as the total number of errors). For example, in a 100: 0 experiment, if there are sufficiently many subjects that the choices on trial 1 can be used to estimate $p$ accurately, then the trials to the first success determine the nonreward parameter $\beta_{2}$. This still leaves the parameter $\beta_{1}$ of the reward operator unspecified.

Now observe that if we go to a final trial, $N$, we can estimate $p_{N}$ from the observed number of choices on that trial, and if we proceed backwards from that trial to the last error, then only the reward operator will be applied during these trials. Thus, $L\left(1-p_{N}, \beta_{1}\right)$ gives the expected number of trials between the last error and the final trial. Matching this expected value to the observed value provides an estimate of $\beta_{1}$.
The method just described does not require that we use the estimated probability on the first and last trials, and in fact we do not. Rather, we used the observed mean learning curve to judge the trial numbers (not necessarily integers) for which the proportion of errors is 0.95 and 0.05 . The mean number of trials to the first success and to the last failure from these trials, respectively, was determined, and $\beta_{1}$ and $\beta_{2}$ were thereby estimated from the table of $L(p, \beta)$, The initial probability, $p_{1}$, was estimated by applying the inverse of the nonreward operator from the 0.95 trial to the first trial. For example, if the 0.95 trial is 8 and $\hat{\beta}_{2}=1.3$, then $v_{y}=0.95 / 0.05=19$ and so $v_{1}=(1.3)^{8}(19)=154.98$. Thus,

$$
p_{1}=\frac{154.98}{155.98}=0.994
$$

The choice of the points 0.95 and 0.05 is based upon two considerations. First, the probability should not be very far from 1 if the inverse of the nonreward operator can be legitimately applied to estimate the initial probability. Second, if $p$ is very near 1 , the mean and variance of the trials to the first success becomes very large, and the estimate of $\beta$ will not be very stable.

| TABLE 1 <br> Comparison of Several Statistics of the Solomon-Wynne Avoidance-Training Data with the Statistics Obtained from Monte Carlo Computations with the Alpha and Beta Models |  |  |  |
| :---: | :---: | :---: | :---: |
| Statistic | Real Dogs Mean S. D. | Alpha Model Stat-Dogs Mean S.D. | Beta Model Stat-Dogs Mean S.D. |
| Trials before first avoidance | $4.50 \quad 2.25$ | 4.132 .08 | 3.931 .74 |
| Trials before second avoidance | $6.47 \quad 2.62$ | $6.20 \quad 2.06$ | $6.40 \quad 1.33$ |
| Total number of shocks | $7.80 \quad 2.52$ | $7.60 \quad 2.27$ | $7.80 \quad 1.10$ |
| Trials before last shock | $11.33 \quad 4.36$ | 12.534 .78 | 13.574 .17 |
| Number of alternations | 5.472 .72 | 5.872 .11 | $6.50 \quad 2.01$ |
| Length of longest run of shocks | $4.73 \quad 2.03$ | 4.331 .89 | $4.30 \quad 1.29$ |
| Trials before first run of four avoidances | 9.704 .14 | 9.473 .48 | 10.133 .00 |

## A Relearning Experiment

The Experiment. Galanter and Bush (Chapter 14) conducted a T-maze experiment in which rats were rewarded whenever they turned right, and were never rewarded when they turned left. This training period continued at a rate of three trials a day for 48 trials. For the next 48 trials, food reward was al-

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 the data in detail. As pointed out earlier, however, without such a check on the estimates there is some ambiguity about their exact values; nonetheless,范 methods to estimate the mean learning curve, estimates lying between 1.02

 appreciably larger than the reward parameter, as was found with the Solomon and Wynne data.

## An Overlearning Experiment





 in the first period and hence the initial probability of error in the second.

This method has the severe drawback that the mean learning curve is fairly flat at these two points, so that the estimated trial numbers are rather sensitive to what smooth curve is passed through the data points. This variability is reflected in a considerable variability of the estimated parameters. It is, therefore, essential that some check be made on the estimates before they are taken too seriously. The one that we use is whether statistics computed from Monte Carlos using the estimates match the corresponding data statistics. A more refined but time-consuming procedure is to determine the
 mate the 0.05 and 0.95 trials, calculate from the data the new mean number of trials to the first success and to the last failure, and then reestimate the
 run and the whole process is repeated a number of times until convergence is obtained.

We now describe three different experiments reported elsewhere. For each of these experiments we estimate parameter values for the beta model. For

 with the experimental data and with previously reported statistics of the alpha model.

An Avoidance-Learning Experiment

 a traumatizing electric shock. Prior to the onset of the shock a discriminative stimulus was presented to the animals, and, provided they had learned, they could vault the barrier and consistently avoid shock. The complete


Parameter Estimation. By using the technique outlined in the preceding section, parameters were estimated. One point of interest should be made. The initial probability of an avoidance, estimated from the first trial of the experiment, is 0.0 . A feature of the beta model is that, unless the initial probability of a success is different from zero, learning will not occur. For pue 'rg әұеu!̣sa of pasn sem [e!
 $\hat{p}_{1}=0.06, \hat{\beta_{1}}=1.2, \hat{\beta_{2}}=1.7$. Monte Carlo computations were then made
-хә әपิ t' perimental data and from the beta-model Monte Carlos, along with the statistics previously reported for the alpha model. In Chapter 15 the corresponding statistics for seven other models are given.
${ }^{3}$ All Monte Carlo computations in this study were done at the Computer Center, University of Pennsylvania. For this purpose, a general program for stochastic learning models was developed by Dr. Saul Gorn and Mr. Peter Z. Ingerman.

Parameter Estimation. We estimated the beta-model parameters for period 2 with the method used before. The values are $\hat{p}_{1}=0.996, \hat{\beta}_{1}=1.10, \hat{\beta}_{2}=1.32$. As found in the previous two experiments, $\hat{\beta}_{2}$ is larger than $\hat{\beta_{1}}$. However, $\hat{\beta}_{2}$ in this experiment is smaller than it was in the previous $T$-maze experiment.
Goodness-of-Fit. As before, Monte Carlo computations were made and various statistics computed. In Table 2, these are compared with corresponding statistics of the data and population values computed from the alpha model. The mean performance curves for the experimental animals and for the Monte Carlo runs are shown in Fig. 1.


FIGURE 1. Period 2 of the overlearning experiment showing the average response frequencies in three-trial blocks for the experimental animals (filled circles) and for the beta-model Monte Carlo analogs (open circles).

TABLE 2
Comparison of Several Statistics of the Overlearning Experiment with Statistics Obtained for the Two Models

| Statistic | Real Rats | Alpha Model <br> (Expected <br> Values) | Beta Model <br> (Stat-Rats) |
| :--- | :---: | :---: | :---: |
| Mean total errors | 24.68 | 24.62 | 24.40 |
| $\quad$ Variance of total errors | 5.01 | 26.57 | 3.33 |
| Mean trials before first success | 13.32 | 12.53 | 14.24 |
| Mean number of error runs | 6.11 | 7.03 | 6.24 |
| Mean error runs of length 1 | 3.11 | 3.63 | 3.32 |
| Mean error runs of length 2 | 0.47 | 1.13 | 0.80 |
| Mean error runs of length 3 | 0.53 | 0.54 | 0.48 |
| Mean error runs of length 4 | 0.32 | 0.32 | 0.20 |
| Mean error runs of length 5 | 0.42 | 0.21 | 0.20 |

## Discussion

One of the more interesting results of the beta-model analyses just presented is that the estimates of the nonreward parameter, $\beta_{2}$, are uniformly larger than the corresponding estimates of the reward parameter, $\beta_{1}$. The alphamodel analyses, on the other hand, lead to the opposite conclusion about the relative effects of reward and nonreward for the first and third experiments described. Therefore, it is evident that one's inferences about the relative effectiveness of reward and nonreward (or avoidance and escape) are " model-bound." If such inferences could be made by using a nonparametric technique which makes no assumptions other than those embodied in a large class of models (including the alpha and beta models), then evidence in support of one model or the other would be obtained. Unfortunately, we have not found a satisfactory technique for this purpose; we must rely on other evidence if we wish to decide which model is the more satisfactory.

We compared the alpha and beta models by analyzing in detail two experiments. The alpha model is in very close agreement with the avoidancelearning data on all properties examined; the beta-model figures are likewise very close to the data, except for the variance of total shocks. Thus, the alpha model has a slight edge on the beta model for these data. On the other hand, the beta model gives a decidedly more satisfactory description of the data on retraining after overlearning. With this experiment, the alpha model appears to be in serious trouble, particularly in predicting the variance of the total number of errors.
The variance of total errors is a very useful statistic for discriminating between the two models. As was pointed out to us by S. Sternberg, this is a consequence of the different roles played by reward and nonreward in the two analyses. When reward is less effective than nonreward, the process has " negative feedback": if an animal receives a large number of rewards during the early trials, his probability of error remains high and so he will make few rewarded responses during the later trials. Similarly, if he makes many
errors early, his probability of error decreases to a low value, and so few errors are made later. This effect tends to equalize the total errors made by different animals. On the other hand, when reward is more effective than nonreward, "positive feedback" exists and so one would expect a large variance of the total number of errors.

If reward and nonreward are assumed to have equal effects, each model predicts a specified variance of total errors; these predictions can serve as baselines in pursuing the argument given in the previous paragraph. Formulas for the mean and variance of total errors for the equal-alpha model are well known (see Chapter 10). For the relearning period of the overlearning experiment, we observed a mean of 24.7. Equating this to the expected value and taking $p_{1}=1$, we estimate $\alpha$ to be 0.96 . The variance is then computed to be 9.9 . For the equal-beta model, ${ }^{4}$ using the observed mean and $p_{1}=0.996$, the value previously obtained for the beta model, we estimate $\beta$ to be 1.25 . This leads to a computed variance of 4.5 . Both of these computed variances are consistent with our arguments about how the relative effects of reward and nonreward alter the variance. The unequal-alpha model with reward more effective led to a variance of 26.6 , compared with the 9.9 figure for the equal-alpha model. The unequal-beta model with nonreward more effective gave a variance of 3.3 , compared with the 4.5 value for the equal-beta model. (All computations fixed the mean total errors at the observed value of 24.7.)

A desirable property of any learning model is that the event parameters should be independent of experimental variables such as the number of trials of previous training. This property has been termed "event invariance" or "parameter invariance" ([1], Chapter 14). As noted in Chapter 14, the alphamodel analyses of the two learning experiments described above do not exhibit this property. Likewise, the beta-model analyses of these same data fail to support the hypothesis of parameter invariance in that model. The data on relearning after overtraining lead to a nonreward parameter that is less effective than that obtained from the data on relearning after moderate training.

Additional evidence for lack of parameter invariance in the beta model is found by examining the data from the first period of the overlearning experiment. Proceeding backwards from the 0.95 point on the learning curve (trial 31), we estimated $\beta_{1}$ to be 1.20. But, when we moved backwards from the end of the first period, using the estimate $\hat{p}_{1}=0.996$ obtained from the
${ }^{4}$ Major simplifications in the beta model result from the special assumption $\beta_{1}=\beta_{2}=\beta$, which implies that reward and nonreward have equal effects. The probability of an error on trial $n$ has the fixed value

$$
p_{n}=p_{1} /\left[p_{1}+\left(1-p_{1}\right) \beta^{n-1}\right]
$$

where $\beta>1$. Defining a random variable $x_{n}$ that has the value 1 when an error occurs on trial $n$ and the value 0 otherwise, we obtain for the total number of errors $u_{1}=\sum x_{n}$ (all summations in this note are from 1 to $\infty$ ). The expected value is
$E\left(u_{1}\right)=\Sigma E\left(x_{n}\right)=\Sigma p_{n}=\Sigma\left\{p_{1} /\left[p_{1}+\left(1-p_{1}\right) \beta^{n-1}\right]\right\}$.
If we replace the sum with an integral from 1 to $\infty$, we obtain the approximation $E\left(u_{1}\right) \cong-\log \left(1-p_{1}\right) / \log \beta$. The variance is
$\operatorname{var}\left(u_{1}\right)=\Sigma \operatorname{var}\left(x_{n}\right)=\sum p_{n}\left(1-p_{n}\right)=\sum\left\{p_{1}\left(1-p_{1}\right) \beta^{n-1} /\left[p_{1}+\left(1-p_{1}\right) \beta^{n-1}\right]^{2}\right\}$.
The integral approximation is $\operatorname{var}\left(u_{\mathrm{I}}\right) \cong p_{1} / \log \beta$.
beginning of the second period, we obtained $\hat{\beta}_{1}=1.015$. Thus, reward seems to have much less effect during the late trials of overlearning than it does anywhere else in the data.
In summary, we have uncovered two pieces of evidence against the beta model from the three experiments analyzed: (a) underestimates of the variance of total errors, and (b) lack of parameter invariance. There are two reasons, however, why we feel that these apparent weaknesses of the model need not be taken too seriously. The first has to do with the experiments themselves. It is reported in Chapter 14 that the data from the two Tmaze experiments, both of which had three trials a day, exhibited a very significant daily recovery effect, at least for the last 48 trials. The extent to which this phenomenon affects the parameter estimates and the various measures of goodness-of-fit is not known, but we would not be surprised if it were quite serious. The second reason for tempering the evidence against the beta model is our implicit assumption of a single unique value of the initial probability for each period of each experiment. Unlike the alpha model, the beta model is extremely sensitive to $p_{1}$ in the neighborhood of 1 or 0 . Therefore, a distribution of $p_{1}$ with very small spread might have a strong effect on subsequent analyses. Furthermore, we know that the model implies a non-zero-variance distribution of $p$ 's at the end of a training period, and therefore at the beginning of the following period. One might hope, therefore, that the apparent evidence against the beta model would disappear when both the experiments and the analyses are refined.

Alternatively, however, the more refined experiments and analyses may continue to exhibit a lack of parameter invariance. In particular, the tail of the learning curve in an overtraining experiment may be considerably flatter than predicted by the beta model with parameters estimated from other regions. (It should be noted that with parameter values of the order of 1.1 , the beta model would predict an initial probability of $0.999,999$ at the beginning of period 2 of the relearning experiment.) If this is the case, then it will be necessary to devise models that exhibit more reduction in the effect of experience as the probability of choice approaches 0 or 1 .

This study represents the first detailed inquiry into the adequacy of the beta model. More such studies are needed before a final evaluation can be made. To facilitate the analyses, further mathematical work on model properties and related estimation problems is needed.
Table of $L(p, \beta)$
The following five-page table of the function

$$
L(p, \beta)=\sum_{k=1}^{\infty} \frac{k \beta^{k}\left[\frac{p}{1-p}\right]^{k}}{\prod_{j=0}^{k}\left[\frac{p}{1-p}+\beta^{j}\right]},
$$

was prepared by the Computer Center, University of Pennsylvania. We are indebted to Dr. Saul Gorn, Director of the Center, and to Mr. Peter Ingerman, who wrote the program.

The references to this chapter follow the table.

|  |  | 1.000 | 1.010 | 1.020 | 1.030 | 1.032 | 1.034 | 1.036 | 1.038 | 1.040 | 1.042 | 1.044 | 1.046 | 1.048 | 1.050 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | . 9995 | 1999.000 | 260.453 | 162.129 | 121.295 | 115.738 | 110.734 | 106.199 | 102.070 | 98.291 | 94.819 | 91.616 | 88.651 | 85.898 | 83.333 |
|  | . 99941 | 1665.667 | 244.650 | 153.709 | 115.520 | 110.301 | 105.597 | 101.331 | 97.442 | 93.882 | 90.607 | 87.584 | 84.785 | 82.183 | 79.759 |
|  | . 99931 | 1427.571 | 231.534 | 146.673 | 110.680 | 105.744 | 101.290 | 97.247 | 93.559 | 90.180 | 87.071 | 84.199 | 81.537 | 79.062 | 76.755 |
|  | . 9992 | 1249.000 | 220.370 | 140.647 | 106.523 | 101.827 | 97.587 | 93.735 | 90.220 | 86.996 | 84.028 | 81.285 | 78.741 | 76.375 | 74.168 |
|  | . 9991 | 1110.111 | 210.685 | 135.387 | 102.886 | 98.400 | 94.345 | 90.660 | 87.294 | 84.206 | 81.361 | 78.730 | 76.290 | 74.019 | 71.899 |
|  | . 9990 | 999.000 | 202.158 | 130.730 | 99.658 | 95.356 | 91.466 | 87.928 | 84.694 | 81.726 | 78.990 | 76.459 | 74.109 | 71.922 | 69.880 |
|  | . 9989 | 908.091 | 194.560 | 126.558 | 96.759 | 92.623 | 88.879 | 85.473 | 82.358 | 79.496 | 76.858 | 74.416 | 72.148 | 70.036 | 68.064 |
|  | . 9988 | 832.333 | 187.725 | 122.786 | 94.133 | 90.145 | 86.534 | 83.246 | 80.237 | 77.473 | 74.923 | 72.561 | 70.368 | 68.324 | 66.414 |
|  | . 9987 | 768.231 | 181.525 | 119.348 | 91.733 | 87.881 | 84.390 | 81.210 | 78.299 | 75.623 | 73.152 | 70.864 | 68.738 | 66.756 | 64.904 |
|  | . 9986 | 713.286 | 175.862 | 116.193 | 89.527 | 85.799 | 82.418 | 79.336 | 76.514 | 73.919 | 71.522 | 69.302 | 67.237 | 65.312 | 63.513 |
|  | . 9985 | 665.667 | 170.660 | 113.281 | 87.487 | 83.872 | 80.593 | 77.603 | 74.863 | 72.342 | 70.013 | 67.854 | 65.847 | 63.975 | 62.224 |
|  | . 9984 | 624.000 | 165.855 | 110.581 | 85.591 | 82.082 | 78.896 | 75.990 | 73.327 | 70.874 | 68.609 | 66.507 | 64.553 | 62.730 | 61.024 |
|  | . 9983 | 587.235 | 161.397 | 108.065 | 83.821 | 80.410 | 77.312 | 74.484 | 71.891 | 69.503 | 67.296 | 65.248 | 63.343 | 61.565 | 59.901 |
|  | . 9982 | 554.556 | 157.245 | 105.712 | 82.163 | 78.843 | 75.827 | 73.072 | 70.545 | 68.217 | 66.065 | 64.067 | 62.208 | 60.472 | 58.848 |
|  | . 9981 | 525.316 | 153.363 | 103.503 | 80.605 | 77.370 | 74.430 | 71.744 | 69.279 | 67.007 | 64.906 | 62.955 | 61.139 | 59.443 | 57.856 |
| ¢ | . 9980 | 499.000 | 149.723 | 101.424 | 79.135 | 75.980 | 73.112 | 70.490 | 68.083 | 65.864 | 63.811 | 61.905 | 60.130 | 58.471 | 56.918 |
|  | . 9975 | 399.000 | 134.381 | 92.572 | 72.845 | 70.030 | 67.465 | 65.117 | 62.957 | 60.963 | 59.114 | 57.396 | 55.793 | 54.295 | 52.890 |
|  | . 9970 | 332.333 | 122.469 | 85.585 | 67.845 | 65.294 | 62.967 | 60.832 | 58.866 | 57.047 | 55.360 | 53.790 | 52.323 | 50.950 | 49.662 |
|  | . 9965 | 284.714 | 112.856 | 79.864 | 63.722 | 61.386 | 59.251 | 57.290 | 55.481 | 53.806 | 52.250 | 50.800 | 49.445 | 48.175 | 46.983 |
|  | . 9960 | 249.000 | 104.879 | 75.054 | 60.234 | 58.077 | 56.102 | 54.286 | 52.609 | 51.054 | 49.608 | 48.259 | 46.997 | 45.814 | 44.701 |
|  | . 9955 | 221.222 | 98.120 | 70.929 | 57.225 | 55.220 | 53.381 | 51.689 | 50.123 | 48.671 | 47.319 | 46.057 | 44.875 | 43.766 | 42.722 |
|  | . 9950 | 199.000 | 92.297 | 67.335 | 54.590 | 52.716 | 50.995 | 49.409 | 47.941 | 46.578 | 45.307 | 44.120 | 43.007 | 41.962 | 40.978 |
|  | . 9940 | 165.667 | 82.728 | 61.341 | 50.163 | 48.504 | 46.978 | 45.568 | 44.261 | 43.044 | 41.909 | 40.846 | 39.849 | 38.911 | 38.027 |
|  | . 9930 | 141.857 | 75.142 | 56.502 | 46.557 | 45.069 | 43.697 | 42.428 | 41.249 | 40.150 | 39.123 | 38.160 | 37.256 | 36.404 | 35.600 |
|  | . 9920 | 124.000 | 68.949 | 52.486 | 43.539 | 42.191 | 40.946 | 39.792 | 38.718 | 37.716 | 36.778 | 35.898 | 35.070 | 34.289 | 33.551 |
|  | . 9910 | 110.111 | 63.775 | 49.082 | 40.963 | 39.731 | 38.592 | 37.534 | 36.549 | 35.628 | 34.765 | 33.954 | 33.191 | 32.470 | 31.788 |
|  | . 9900 | 99.000 | 59.377 | 46.150 | 38.728 | 37.595 | 36.546 | 35.570 | 34.660 | 33.809 | 33.010 | 32.258 | 31.550 | 30.881 | 30.247 |
|  | . 9850 | 65.667 | 44.427 | 35.871 | 30.766 | 29.967 | 29.222 | 28.526 | 27.873 | 27.259 | 26.680 | 26.133 | 25.616 | 25.125 | 24.658 |
|  | . 9800 | 49.000 | 35.643 | 29.556 | 25.755 | 25.149 | 24.581 | 24.048 | 23.546 | 23.072 | 22.624 | 22.198 | 21.795 | 21.410 | 21.044 |
|  | . 9750 | 39.000 | 29.797 | 25.211 | 22.242 | 21.761 | 21.310 | 20.884 | 20.481 | 20.100 | 19.738 | 19.394 | 19.066 | 18.754 | 18.455 |
|  | . 9700 | 32.333 | 25.603 | 22.011 | 19.614 | 19.221 | 18.851 | 18.500 | 18.168 | 17.853 | 17.553 | 17.267 | 16.994 | 16.733 | 16.483 |
|  | . 9650 | 27.571 | 22.438 | 19.542 | 17.561 | 17.232 | 16.922 | 16.627 | 16.348 | 16.081 | 15.827 | 15.585 | 15.353 | 15.131 | 14.918 |
|  | . 9600 | 24.000 | 19.958 | 17.572 | 15.904 | 15.626 | 15.361 | 15.109 | 14.870 | 14.641 | 14.423 | 14.214 | 14.014 | 13.822 | 13.638 |
|  | . 9550 | 21.222 | 17.961 | 15.961 | 14.536 | 14.296 | 14.067 | 13.850 | 13.642 | 13.444 | 13.254 | 13.072 | 12.897 | 12.729 | 12.568 |
|  | . 9500 | 19.000 | 16.317 | 14.616 | 13.384 | 13.175 | 12.975 | 12.785 | 12.603 | 12.429 | 12.262 | 12.102 | 11.947 | 11.799 | 11.657 |
|  |  | 1.052 | 1.054 | 1.056 | 1.058 | 1.060 | 1.062 | 1.064 | 1.066 | 1.068 | 1.070 | 1.075 | 1.080 | 1.085 | 1.090 |
|  | . 9995 | 80.938 | 78.696 | 76.591 | 74.612 | 72746 | 70.984 | 69.318 | 67.739 | 66.241 | 64.817 | 61.547 | 58.635 | 56.023 | 53.667 |
|  | . 9994 | 77.493 | 75.371 | 73.378 | 71.503 | 69.735 | 68.065 | 66.484 | 64.986 | 63.564 | 62.212 | 59.106 | 56.337 | 53.852 | 51.609 |
|  | . 9993 | 74.598 | 72.576 | -70.677 | 68.889 | 67.203 | 65.609 | 64.101 | 62.671 | 61.312 | 60.021 | 57.051 | 54.403 | 52.025 | 49.876 |
|  | . 9992 | 72.104 | 70.168 | -68.349 | 66.637 | 65.020 | 63.493 | 62.046 | 60.674 | 59.371 | 58.131 | 55.279 | 52.734 | 50.447 | 48.380 |
|  | . 9991 | 69.916 | 68.056 | 66.307 | 64.660 | 63.105 | 61.635 | 60.242 | 58.921 | 57.666 | 56.471 | 53.722 | 51.268 | 49.062 | 47.066 |
|  | . 9990 | 67.969 | 66.176 | 6 64.489 | 62.900 | 61.400 | 9.981 | 58.636 | 57.360 | 56.147 | 54.993 | 52.336 | 49.962 | 47.827 | 45.895 |
|  | . 9989 | 66.217 | 64.484 | 62.853 | 61.316 | 59.865 | 58.491 | 57.189 | 55.954 | 54.779 | 53.661 | 51.086 | 48.785 | 46.713 | 44.839 |
|  | . 9988 | 64.626 | 62.947 | 61.367 | 59.877 | 58.469 | 57.137 | 55.875 | 54.676 | 53.536 | 52.450 | 49.950 | 47.714 | 45.701 | 43.878 |
|  | . 9987 | 63.169 | 61.539 | +60.005 | 58.558 | 57.191 | 55.897 | 54.670 | 53.505 | 52.396 | 51.341 | 48.908 | 46.732 | 44.772 | 42.997 |
|  | . 9986 | 61.826 | 60.242 | - 58.750 | 57.343 | 56.013 | 54.754 | 53.559 | 52.425 | 51.346 | 50.317 | 47.948 | 45.826 | 43.915 | 42.183 |
|  | . 9985 | 60.582 | 59.040 | - 57.587 | 56.217 | 54.921 | 53.694 | 52.529 | 51.423 | 50.371 | 49.368 | 47.056 | 44.986 | 43.120 | 41.429 |
|  | . 9984 | 59.424 | 57.920 | 56.504 | 55.167 | 53.903 | 52.706 | 51.570 | 50.490 | 49.463 | 48.484 | 46.226 | 44.203 | 42.379 | 40.725 |
|  | . 9983 | 58.341 | 56.873 | - 55.491 | 54.186 | 52.951 | 51.782 | 50.672 | 49.617 | 48.613 | 47.656 | 45.448 | 43.469 | 41.685 | 40.066 |
|  | . 9988 | 57.323 | -55.890 | 54.539 | 53.264 | 52.057 | 50.914 | 49.828 | 48.796 | 47.814 | 46.878 | 44.717 | 42.780 | 41.032 | 39.446 |
|  | . 9981 | 56.366 | -54.964 | 53.643 | 52.395 | 51.215 | 50.096 | 49.033 | 48.023 | 47.062 | 46.145 | 44.028 | 42.130 | 40.417 | 38.862 |
| ¢ | . 9980 | 55.461 | 54.089 | - 52.796 | 51.574 | 50.418 | 49.322 | 48.282 | 47.292 | 46.350 | 45.451 | 43.377 | 41.515 | 39.835 | 38.309 |
|  | . 9975 | 51.569 | 50.326 | 49.152 | 48.042 | 46.991 | 45.994 | 45.046 | 44.144 | 43.284 | 42.464 | 40.568 | 38.864 | 37.324* | * 35.924 |
|  | . 9970 | 48.450 | 47.308 | 46.228 | 45.207 | 44.239 | 43.320 | 42.446 | 41.613 | 40.819 | 40.061 | 38.307 | 36.729 | 35.300 | 34.000 |
|  | . 9965 | 45.859 | 44.800 | 43.798 | 42.850 | 41.950 | 41.095 | 40.281 | 39.506 | 38.766 | 38.059 | 36.422 | 34.948 | 33.611 | 32.393 |
|  | . 9960 | 43.653 | 42.663 | 41.727 | 40.839 | 39.997 | 39.196 | 38.434 | 37.707 | 37.013 | 36.349 | 34.811 | 33.424 | 32.166 | 31.018 |
|  | . 9955 | 41.737 | 40.807 | 39.927 | 39.092 | - 38.299 | 37.545 | 36.827 | 36.141 | 35.486 | 34.860 | 33.408 | 32.096 | 30.905 | 29.818 |
|  | . 9950 | 40.050 | 39.172 | 38.341 | 37.552 | 36.802 | 36.088 | 35.408 | 34.759 | 34.139 | 33.545 | 32.167 | 30.922 | 29.790 | 28.756 |
|  | . 9940 | 37.191 | 36.400 | 35.650 | 34.938 | 34.261 | 33.615 | 32.999 | 32.411 | 31.848 | 31.310 | 30.057 | 28.923 | 27.891 | 26.946 |
|  | . 9930 | 34.839 | 34.118 | - 33.434 | 32.784 | 32.165 | 31.574 | 31.011 | 30.472 | 29.956 | 29.462 | 28.311 | 27.268 | 26.317 | 25.445 |
|  | . 9920 | 32.853 | 32.190 | -31.561 | 30.962 | 30.391 | 29.847 | 29.326 | 28.829 | 28.352 | 27.895 | 26.829 | 25.862 | 24.979 | 24.169 |
|  | . 9910 | 31.142 | 30.529 | 29.946 | 29.391 | 28.861 | 28.355 | 27.872 | 27.409 | 26.965 | 26.540 | 25.547 | 24.644 | 23.819 | 23.062 |
|  | . 9900 | 29.646 | 29.075 | - 28.532 | 28.015 | 27.521 | 27.048 | 26.597 | 26.164 | 25.749 | 25.351 | 24.421 | 23.574 | 22.799 | 22.087 |
|  | . 9850 | 24.214 | 23.791 | 23.386 | 23.000 | 22.630 | 22.276 | 21.936 | 21.610 | 21.296 | 20.994 | 20.286 | 19.638 | 19.043 | 18.493 |
|  | . 9800 | 20.695 | 20.361 | 20.041 | 19.735 | 19.441 | 19.159 | 18.888 | 18.626 | 18.375 | 18.133 | 17.563 | 17.039 | 16.556 | 16.108 |
|  | . 9750 | 18.170 | 17.896 | 17.634 | 17.382 | 17.140 | 16.907 | 16.683 | 16.466 | 16.258 | 16.056 | 15.582 | 15.144 | 14.739 | 14.362 |
|  | . 9700 | 16.243 | 16.014 | 15.793 | 15.581 | 15.376 | 15.179 | 14.989 | 14.806 | 14.629 | 14.458 | 14.053 | 13.679 | 13.331 | 13.008 |
|  | . 9650 | 14.713 | 14.516 | -14.327 | 14.145 | 13.969 | 13.800 | 13.636 | 13.478 | 13.325 | 13.176 | 12.826 | 12.501 | 12.198 | 11.915 |
|  | . 9600 | 13.460 | 13.290 | 13.125 | 12.967 | 12.814 | 12.666 | 12.523 | 12.384 | 12.250 | 12.120 | 11.812 | 11.526 | 11.259 | 11.009 |
|  | . 9550 | 12.412 | 12.262 | 12.118 | 11.978 | 11.843 | 11.713 | 11.586 | 11.464 | 11.345 | 11.230 | 10.957 | 10.702 | 10.465 | 10.242 |
|  | . 9500 | 11.519 | 11.386 | 11.258 | 11.134 | 11.014 | 10.898 | 10.785 | 10.676 | 10.570 | 10.467 | 10.223 | 9.995 | 9.781 | 9.581 |

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| $106 \cdot 7$ | $81 \square^{\circ} \mathrm{E}$ | $\varepsilon L c^{\prime} \varepsilon$ | $6 S L^{\prime} \varepsilon$ | 786． 8 | 911＊ | $597^{\circ}$ ¢ | $\varepsilon \underbrace{\circ} \square^{\circ}$ | Lz9＇ | 2IL | ع08＇ | 106．${ }^{\text {b }}$ | 500．9 | $91{ }^{\prime} \cdot \mathrm{S}$ | 0056 ． |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $600 \cdot 8$ | 999＇$\varepsilon$ | $02 L^{\circ} \mathrm{E}$ | LI6．$¢$ | LST＇$\ddagger$ | L62＊ | 9G＊＊ | 989 ${ }^{\circ}$ | \＆ャ8＇ | ャ¢6＊ | 280 ${ }^{\circ}$ | 9EI＇G | $\angle 巾 \% \cdot 9$ | L98．g | 0SS6． |
| $0 ¢ \tau^{\circ} \mathrm{E}$ | $01 /{ }^{\circ} \mathrm{E}$ | $988 . \varepsilon$ | $960^{\circ}$ ¢ | ZSE＊ | 209＊＊ | 229＊ | c98＇ | $280 \cdot \mathrm{G}$ | 981＇ 9 | I62\％ | ع0＊${ }^{\circ} \mathrm{S}$ | \＆Z9＇s | IS9＇9 | $0096{ }^{\circ}$ |
| 897.8 | $\angle 88^{\circ} \mathrm{E}$ | SLO ${ }^{\circ}{ }^{\circ}$ | 008＇$\ddagger$ | gLS ${ }^{\circ}$ | LEL＇巿 | $076{ }^{\circ}$ | \＆ZI＇S | $89 \varepsilon^{-} \mathrm{G}$ | SLV＇${ }^{\text {S }}$ | 889＇9 | $0 \mathrm{LL} L^{-} \mathrm{S}$ | ${ }^{078}{ }^{\circ} \mathrm{C}$ | $086 \cdot 5$ | $0 \mathrm{C96}{ }^{\circ}$ |
| $827 \cdot 8$ | ع60 ${ }^{\circ}$ | $962^{\prime}$ D | $68 \varsigma^{\prime}$ | 988＊ | ［10．g | 012.9 | 98＊＇G | $269{ }^{\circ} \mathrm{G}$ | \＆18 ${ }^{\circ} \mathrm{S}$ | L86． 9 | 020＇9 | 2I2＇9 | S98．9 | 0026 ${ }^{\circ}$ |
| 619.8 | $688^{\circ}{ }^{\text {¢ }}$ | 659. | عZ8＇${ }^{\text {¢ }}$ | $8 \mathrm{tI} \cdot 9$ | $0 \pm \varepsilon \cdot 9$ | LSS＇s | ¢08．9 | $260 \cdot 9$ | 0zz：9 | LSE．9 | $\mathrm{cos}^{-9} 9$ | 099.9 | $678 \cdot 9$ | OSL6． |
| ¢ç ${ }^{\circ} \mathrm{\varepsilon}$ | で9＊ | 788＇ | 9LI＇s | tcs 9 | $\angle \sqcap 2 \cdot 9$ | 886.9 | ¢97．9 | ¢8¢ 9 | $\angle Z L \cdot 9$ | 088.9 | ¢п0． 2 | $617^{\circ} \mathrm{L}$ | $600^{\circ} \mathrm{L}$ | 0086. |
| LST＇ | $L \varepsilon 0^{\circ} \mathrm{G}$ | $808^{\circ} \mathrm{S}$ | $9 \mathrm{E} 9^{\circ} \mathrm{G}$ | 0ヶ0．9 | 082．9 | ¢Sc ${ }^{\circ} 9$ | 998.9 | $0 ¢ 2^{\circ}$ | ع68．${ }^{\circ}$ | L99．$L$ | †GL $L^{\circ} \mathrm{L}$ | ¢96． 4 | ZLI＇8 | $09866^{\circ}$ |
| 889＇${ }^{\text {¢ }}$ | $665^{\circ} \mathrm{S}$ | EI6．9 | \＆62＇9 | \＆9\％＇9 | £ $0 \cdot L$ | ع98． 2 | $0 \varepsilon L^{\circ} \angle$ | 6ST＇8 | LSE． 8 | LSG．8 | 8LL＇8 | 210.6 | SL2\％ 6 | $0066{ }^{\circ}$ |
| 002＊ | $972 \cdot \mathrm{c}$ | ［LO＇9 | c97＇9 | ES6． 9 | ゆも\％＇L | $929^{\circ} \mathrm{L}$ | 856.2 | ع0¢ ${ }^{\circ} 8$ | ع09＊ 8 | L18．8 | $8 \downarrow 0.6$ | L62． 6 | 999 6 | $0166^{\circ}$ |
| $978{ }^{\text { }}$ | ［16．9 | $6 \downarrow 2 \cdot 9$ | 899．9 | $991 \cdot L$ | 690． 2 | ¢18． 2 |  | 829．8 | 288.8 | 0116 | IS8， 6 | I19．6 | 868.6 | 0766 ${ }^{\text {．}}$ |
| 026． | $860 \cdot 9$ | LS¢9 | 828.9 | 800＇L | 92L ${ }^{\circ}$ | 980.8 | cos＇8 | I66．8 | 012＇6 | 㭌＇6 | 269.6 | 026.6 | $992^{\circ} 0 \mathrm{I}$ | $0866^{\circ}$ |
| SEI｀ | ¢1¢．9 | －89＊9 | 2EI＇L | $689 . L$ | 170.8 | 20＊ 8 | ［78．8 | ゅ¢¢ 6 | ¢89 ${ }^{\circ} 6$ | 2¢8．6 | $660^{\circ} \mathrm{I}$ | 288．01 | $669^{\circ} 01$ | ${ }^{0} 766^{\circ}$ |
| LE¢ ${ }^{\circ} \mathrm{G}$ | ELS＇9 | 296.9 | ゅセぢL | $270 \cdot 8$ | TLE＇8 | $9 L L^{\prime} 8$ | Lワて．6 | 98.6 | $080 \cdot 01$ | ع62．01 | LLs 01 | \＆88．01 | ¢tz＇II | $0966{ }^{\circ}$ |
| $\mathfrak{G t b}$ ¢ | zzL＇9 | zZI＇L | $609 . L$ | SIz＇8 | $82 \mathrm{~S}^{\prime} 8$ | 66．8 | †Lt 6 | 980．01 | $682^{\circ} 01$ | ［98．01 | セS801 | ILI＇IL | SIS ${ }^{\text {dil }}$ | c966 ${ }^{\circ}$ |
| zLS ${ }^{\circ} \mathrm{S}$ | 688.9 | $208 . L$ | 908． L | 2¢ち 8 | 208．8 | LEz．6 | 玌 26 | LIEOI | 62S 01 | 198．01 | 991＇II | 26\％．II | 198．II | $0966{ }^{\circ}$ |
| 914＇s | $820^{\circ} \mathrm{L}$ | Los．$L$ | $870 \cdot 8$ | 829．8 | $890 \cdot 6$ | DIS 6 | ［E0．0］ | LE9 ${ }^{\circ} \mathrm{I}$ | 606.01 | E0Z 11 | 6IS＇II | 298．IL | EEZ＇ZI | S966． |
| ¢88＇9 | $862^{\circ} \mathrm{L}$ | $\varepsilon \square^{\circ} \mathrm{L}$ | 982.8 | ع96．8 | 698.6 | SE8＊ 6 | ＋LE＇01 | 200＊II | 762＇II | 869＇ 11 | 676．IL | 882＇ ZI | L29＇2I | $0 \angle 66^{\circ}$ |
| $080 \cdot 9$ | LSG＇L | $820 \cdot 8$ | ［69＇8 | $00{ }^{6} 6$ | $92 L^{\circ} 6$ | ¢120 0 | 182．01 | 9t巾 11 | StL＇II | 890.71 | 91＊ CI | ع6L 2 I | ع0Z＇EI | SL66． |
| z28．9 | $928 . \mathrm{L}$ | L98．8 | 996.8 | DIL＇6 | ¢91．01 | 189.01 | 182＇1I | 986 ${ }^{\text {1 }}$ I | E0E 21 | St9＇ 2 L | †L0＇EL | ¢1゙とI | $05^{\circ} \mathrm{E}$ I | $0866^{\circ}$ |
| LLE．9 | $676 . L$ | 97ヵ．8 | ZS0＇6 | 018.6 | 99201 | 68200 | 968＇II | 601＇2I | LとャてI | 8LL＇ZI | ZSI＇EI | 8S9＇EL | $666^{\circ} \mathrm{EI}$ | L866． |
| $98 \dagger \cdot 9$ | L20．8 | 629.8 | £tr ${ }^{6}$ | 016.6 | 2LE0I | 206.01 | LIS＊II | 0もて＇2I | L9C＇ ZI | 816． 21 | $86 \chi^{\prime} \varepsilon 1$ |  | LSI＇tI | $7866{ }^{\circ}$ |
| 867＇9 | 801＊8 | LI9．8 | $68 \chi^{\circ} 6$ | LIO OI | 98t．01 | 270 II | 9b9＇II | 6LE＇ZL | 0tL＇ZI | 990.81 | ZSt ${ }^{\text {ct }}$ | 698.81 |  | £866 ${ }^{\circ}$ |
| ¢99．9 | 9618 | ［1L＊8 | โ¢\＆ 6 | $081{ }^{\circ} \mathrm{OI}$ | S09．01 | 6けI＇II | Z8L＇II | 98S 2 I | 298 ${ }^{\text {Z }}$ | ャZ2＇EI | ¢19 ${ }^{\text {c }}$ ¢ |  | 00S＇it | †866＊ |
| เ¢9＇9 | L82．8 | ［18．8 | $0 \mathrm{OSF}^{6} 6$ | 09200 | 28L ${ }^{\circ} 0$ | 988． 11 | L26． 11 | \＆89 ${ }^{\text {2I }}$ |  | 268．$\varepsilon 1$ | 68L＇¢I | 0zz＇ti | 889＇ t I | $9866{ }^{\circ}$ |
| 604.9 | $988^{\circ} 8$ | L16．8 | 999．6 | 6 LE ． 01 | 898.01 | 0¢ち＇II | ¢80＇ ZI | 198． ZI |  | LLS＇EI | ¢L6．8I |  | 068． ¢ $^{\text {d }}$ | 9866. |
| $68 L^{\circ} 9$ | 267．8 | $280 \cdot 6$ | ［69＇6 | LIS 01 | ¢ $10 \cdot 1$ | 985＇II | 092＇2I | I $80 \cdot \varepsilon$ ¢ | $88 \varepsilon^{\circ} \mathrm{EI}$ |  | SLI tI | 129 ${ }^{\text {¢ }}$－ | 901＇GI | $\angle 866{ }^{\circ}$ |
| 928.9 | L09＊8 | 9st ${ }^{\circ} 6$ | 978.6 | 999.01 | ELI＇II | ¢GL | 0Et＇ZI | $972 \cdot 1$ | 985＇EI | EL6 EI | 268 ${ }^{\text {b }}$ | 958． 1 | LtE＇SI | 8866. |
| ［L6．9 | 2EL ${ }^{\circ}$ | 062.6 | $\varepsilon \angle 6.6$ | $678{ }^{\circ} 01$ | ¢f¢ 11 | 886． 11 | 979＇2I | 8¢ヶ¢ $¢$ I | ¢08＇\＆I | 007＇tI | Lz9＇$\dagger$ I | 160＇GI | 969＊SI | $6866^{\circ}$ |
| SLO ${ }^{\circ}$ | 698.8 | $88 \vdash^{\bullet} 6$ | ャ¢1．01 | L00＇II | ゅEC＇IL | 681 ZI | 2ヶ8＇ ZI | 029 ${ }^{\circ} \mathrm{EL}$ | St0 ${ }^{\text {¢ }}$ | 6もずす | 988＇tI | 6SE＇SI | SL8＇ $\mathrm{SI}^{\text {I }}$ | ${ }^{0666}{ }^{\circ}$ |
| $681^{\circ} \mathrm{L}$ | $020 \cdot 6$ | 109.6 | ZIE 01 | b0z II | 2¢ $2 \cdot 11$ | 198 zI | 080 ¢ 1 | 876 ع 1 |  | ャてL゙ゅI | ILI＇GI | 9¢9．${ }^{\text {cI }}$ | ¢81－91 | I666． |
| LIE ${ }^{\circ}$ | 68I 6 | †8L．6 | Its．0］ | SZt＇II | 926 ${ }^{\text {II }}$ | 609＇ Z | 918．$¢ 1$ | ¢LZ＇ヤI | 809＊$\dagger 1$ | 280 ${ }^{\text {SI }}$ | L67＇SI | 886. SI | $08 S^{\prime} 91$ | 7666 ${ }^{\circ}$ |
| ع97＊ | ［88．6 | 166.6 | LEL＇0 | ¢ 29.1 It | โャて ZI | $268{ }^{\text {Z }} \mathrm{I}$ | 6ヶ9 ${ }^{\circ} \mathrm{EL}$ | 2ヶS ${ }^{\text {² }}$ | 976．${ }^{\text {¢ }}$ | 288．9I | ¢ 98.91 | ¢98．91 | عZ6．91 | ¢666 ${ }^{\circ}$ |
| $0 ¢ 9.2$ | 209.6 | 0ezol | $866^{\circ} 01$ | ${ }^{\text {596．}}$ IL | Ltc． 2 I | LIZ EI | $866^{\circ}$ EI | 616. | 98E ${ }^{\text {gI }}$ | 98L． 91 | ELZ 91 | 108．91 | LLE 2 I | ${ }^{ \pm} 6666^{\circ}$ |
| 678.2 | ¢98．6 | \＆IS 01 | LOE＇II | $908^{\circ} \mathrm{ZI}$ | 606 2I | ع09 $¢ 1$ | でわ゙かし | 998＇SI | 864＇SI | ャ92．91 | 692．91 | LEE 21 | 916． 21 | 9666 ${ }^{\circ}$ |
| $009^{\circ} 7$ | $000 \cdot$ \％ | 006.1 | 008.1 | 002：I | OS9 ${ }^{\circ} \mathrm{I}$ | 009 I | OSS•I | $00{ }^{\prime} \cdot 1$ | 08\％${ }^{\circ}$ | 09\％${ }^{\circ}$ I | $0 巾^{\circ} \cdot 1$ | $0 \overbrace{}^{\prime}$＇ | 00\％${ }^{\text {I }}$ |  |


[^0]:    * Interpolated value

